ELECTRICAL CONNECTIONS

The RHT-DM (Duct Mount) model transmitter should be installed with a flange. This flange is first screwed onto the duct wall and the transmitter probe is then inserted into the flange central hole and locked. Figure 04 below shows flange dimensions and holes. Available in stainless

steel or polyamide 6.6.

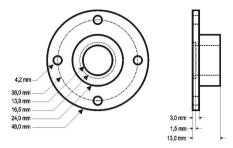


Figure 04 - Mounting flange for RHT/DM

The probe is made in stainless steel, with standard lengths of 150mm and 250mm.

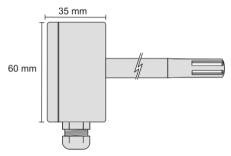


Figure 05 - Model RHT/DM dimensions.

The model RHT/WM (Wall Mount) was designed to be mounted directly onto a wall. With the cover off, the user can access the 2 fixing points and the signal connector, as shown in Figure 06. The transmitter sensor capsule must be placed faced down in order to assure the specified accuracy and protection level.

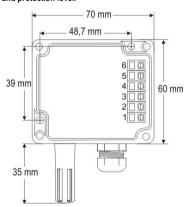


Figure 06 - RHT/WM fixing holes and housing dimensions.

The transmitter can be ordered as 4-20 mA current output or 0 to 10 Vdc voltage output. The output signal is defined on purchase and cannot be later changed.

Variables can be monitored together or separately. Combinations of mobile jumpers J4 and J5 within the transmitter case define how variables will be used. The jumpers also define the transmitter terminals with available output signals.

Jumper J5	Jumper J4	OUT1	OUT2
Position A	Position A	Temperature	Humidity
Position A	Position B	Temperature	Off
Position B	Position A	Humidity	Off
Position B	Position B	Humidity	Temperature

Table 1 - Configuration of OUT1 and OUT2 outputs

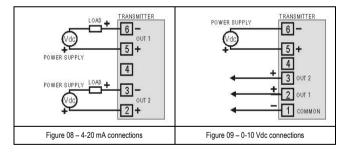


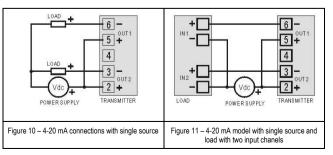
Figure 07 - J4 and J5 position within the transmitter

Figures 08 and 09 show the required electrical connections.



Check that loop OUT1 must always be powered in 4-20 mA model!





LOAD represents the output signal measurement equipment (controller, register, etc).

The connection wires go inside the transmitter trough to the cable gland mounted in the transmitter case

RHT-WM and RHT-DM

OPERATING MANUAL





Man 5000232

WARRANTY

The manufacturer will grant to the owner of his equipment, duly identified through the purchase invoice, a twelve-month warranty under the following terms:

- 1. The one year warranty begins on the day of shipment as stated on the sales bill
- 2. During the warranty period all costs of material and labor will be free of charge provided that the instrument does not show any evidence of misuse.
- 3. For maintenance, return the instrument with a copy of the sales bill to our factory. All transportation and insurance costs should be covered by the owner of the equipment.
- Should any sign of electrical or mechanical shock, abuse, bad handling or misuse be evident the warranty voids and maintenance costs will be charged.

INSTALLATION RECOMMENDATIONS

- · Conductors of small electrical signals must be distant from activation or high-tension/current conductors, preferably passing through grounded conduits.
- A specific electrical power supply network should be provided for instruments use only.
- In controlling and monitoring applications, possible consequences of any system failure must be considered in advance.
- RC filters (47 R and 100 nF, serial) in inductor charges (contactors, solenoids, etc.) are recommended.

ATTENTION

The calibration of the humidity sensor may change in case it is exposed to contaminating vapors or to high humidity and temperature conditions for extended periods. In order to speed up the calibration restoration, proceed as described below:

- Remove the sensor from the capsule.
- Wash it with water in case there are solid particles on it.
- Place it within a 80 °C (+-10 °C) oven for 24 hours
- Place it for 48 hours in a place with a temperature between 20 and 30 °C and humidity over
- Place the sensor back in the capsule.

SPECIFICATIONS

Humidity measurement:

Accuracy: Refer to Figure 01;

Repeatability: ± 1 % RH; Non-linearity: << 1 % RH; Stability: <1 % RH / year;

Span: any value between 0 and 100 % RH or -100 and 103 °C for dew point;

Response time: 4 seconds in slow moving air (63 %);

Temperature channel:

Accuracy: Refer to Figure 01;

Repeatability: ±0.1 °C;

Response time: up to 30 seconds in slow moving air (63 %);

General specifications:

Power supply: 12 Vdc to 30 Vdc (4-20 mA model)

18 to 30 Vdc / 15 mA. (0-10 V model)

Outputs: 4-20 mA or 20-4 mA current, 2-wire *loop* power supply;

0-10 Vdc / 2 mA max. (0-10 V model)

Output Load (RL): 4-20 mA output: RL (Ohms max.) = (Vdc - 12) / 0.02

let Vdc = Loop power supply (12 to 30 Vdc).

0-10 Vdc output: 2 mA max.

OUT1 output resolution: 0.006 mA (4-20 mA) or 0.003 V (0-10 V); OUT2 output resolution: 0.022 mA (4-20 mA) or 0.015 V (0-10 V);

Channel isolation: the 4-20 mA outputs are isolated from each other. The 0-10 V outputs

share a common ground;

Reverse polarity protection: YES

Protection: Electronic circuit case: IP65; Sensors capsule: IP40

Cable entrance: Compress fitting PG7:

Operating limits: Sensor and probe (RHT/DM): see Figure 01;

Electronic circuit: -10 to +65 °C, 0 to 95 % RH.

IMPORTANT NOTE:

The transmitter sensor may be damaged or lose calibration if it is exposed to aggressive atmospheres with high concentrations as Chloride Acid, Nitride Acid, Sulphuric Acid and Ammonia. Acetone, Ethanol and Propylene Glycol may cause reversible measurement errors.

Measures accuracy and sensor operating limits:

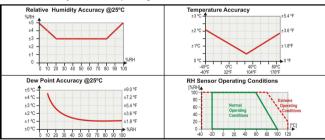


Figure 01 - RH and Temperature accuracies

CONFIGURATION

If the default configuration or the ordered configuration satisfies the application, then no further configuration is necessary and the transmitter is ready to be used. If a new setting is desired, this can be accomplished by the TxConfig and sent to the transmitter through the TxConfig interface.

The TxConfig Interface and Software compose the **Transmitter Configuration Kit**, with can be purchased separately from the manufacturer or one of its distributors. The latest release of this software can be downloaded from our web site. To install, run the **Tx_setup.exe** and follow the instructions

The TxConfig interface connects the transmitter to the PC, as shown in Figures 02 and 03. There are two types of interface: TxConfig-RS232 and TxConfig-USB.

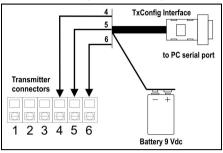


Figure 02 - TxConfig Interface connections model RS232

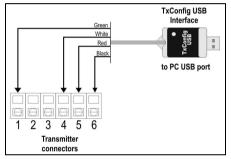


Figure 03 - TxConfig Interface USB connections

Once the connection is accomplished, the software shows the configuration options of the transmitter model attached. Access the Help for usage instructions.

Figure 04 shows the TxConfig sotware main screen

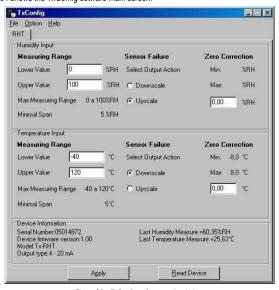


Figure 04 - TxConfig software main window

The fields in the screen mean:

 Measuring Range: Defines the output scale for the input sensor. Program here the measurement Lower Range Value and the Upper Range Value.

The values configured in these fields can not be beyond the **sensor measuring** range. The **minimal span** value has to be observed as well.

When the lower limit is defined with a value higher than the Higher Limit the output current operates from 20 to 4 mA.

- Sensor Failure: establishes the transmitter output behavior (upscale or down-scale) in the
 presence of a sensor fail. When Minimum is selected, the output current is < 4 mA (downscale), typically used for refrigeration. When Maximum is selected, the output current is > mA
 (up-scale), typically used in heating systems.
- 3. Zero Correction: Allows for small sensor corretions.
- Device Information: Transmitter identification data. These information must be informed when the user contact us.
- 5. **Read Device**: Brings to the screen the current transmitter parameters configuration.
- 6. Apply: Sends a new configuration to the transmitter.

Note: The factory default configuration is (unless othenrwise specified or ordered):

- RHT sensor, temperature span 0 to 100 °C and humidity span 0 to 100 % RH;
- 0 °C of zero correction;
- Upscale when sensor fails.

It is important to notice that the transmitter accuracy is always based on the total span of the used sensor, even if a narrower range is configured. Example:

Humidity sensor has a total span of 0 to 100 % and accuracy of 3% at 25 $^{\circ}$ C, as showed in Figure 01. This 3 % RH error is the same no matter if the total span is configured (0 to 100%) or a narrower span (like 20 to 80%).

During configuration, the transmitter needs to be electrically powered. TxConfig-USB interface can provide the power to the transmitter, but this also depends on the used computer hardware.

The TxConfig-RS232 interface, however, requires an auxiliary supply for guarantee reliable communication with the computer. An external 9V battery can be used for this purpose (Figure 02). An alternative is to configure the transmitter while it is in operation; this way, the needed energy is supplied by the current loop. See Figure 05.

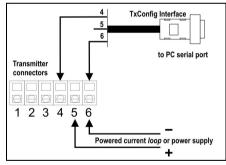


Figure 05 - TxConfig Interface connections - Loop powered



The TxConfig interfaces contain dedicated circuitry for proper communication between transmitters and computer. Always make use of the TxConfig interfaces for configuration purposes, otherwise the transmitters may get damaged, voiding the warranty.

Serial port configuration errors may occur when other software are sharing the same serial port. Close all serial port applications prior to using the TxConfig software.